

BINARY SEARCH TREE

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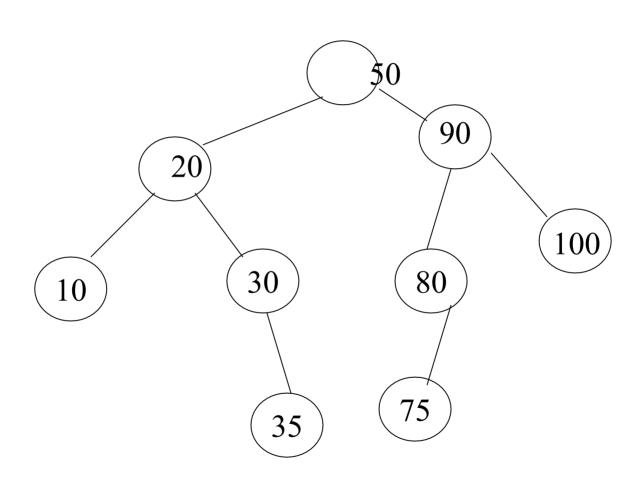


Binary Search Tree (BST)

- A BST is a binary tree T with the following conditions:
 - a)Key of every node in the right sub-tree of T is greater then the Key at root.
 - b)Key of every node in the left sub-tree of T is less then the Key at root.
- c) All Keys are distinct.



An Example





BST Operations

1. Search for a key

2.Insert a key 3.Delete a

key 4.Findmax &

Findmin

5. Find the Kth max or min



Recursive Search

```
BST * search (T key, BST * t){ if (empty_t(t)) return NULL; else if (key==t→info) return t; else if (key < t→info) return (search (key,t→left)); else return (search (key, t→right));}
```

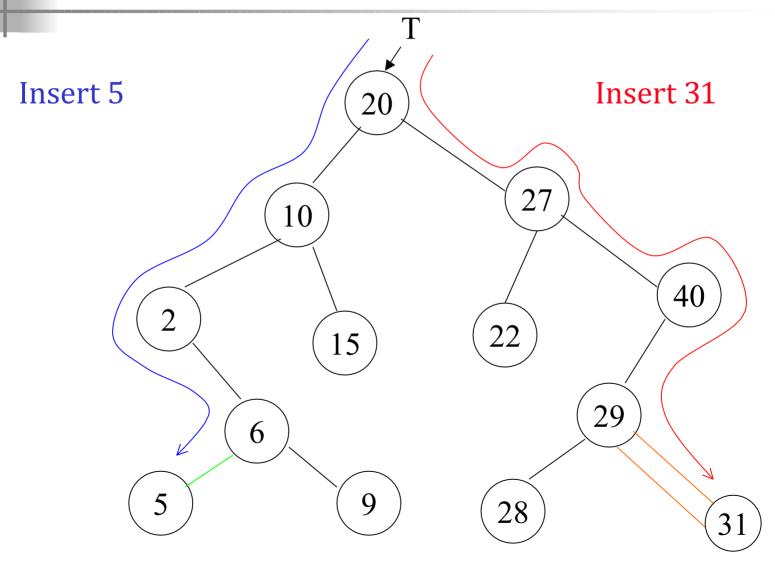


Non-recursive Search

```
BST * search (T key, BST * t) { BST
 *cur; int found;
 if (empty t(t)) return NULL;
else{
   cur=t; found=0;
      while (cur!=NULL) & (!(found))){
          if (key==cur \rightarrow info) found=1;
                else if (key < cur\rightarrowinfo)
                            cur=cur→left;
                  else cur=cur→right;
           return cur;
```



Insertion Example



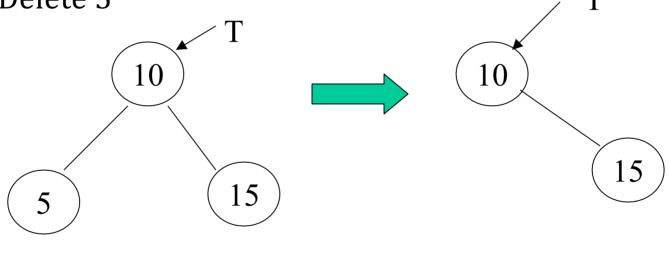


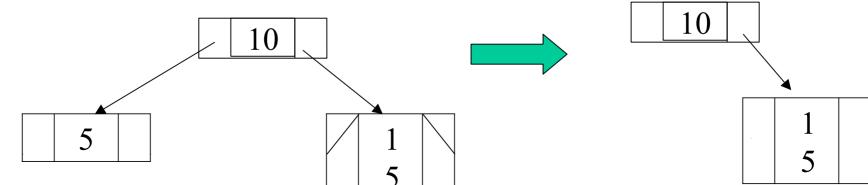
Deletion Example

• Delete 5

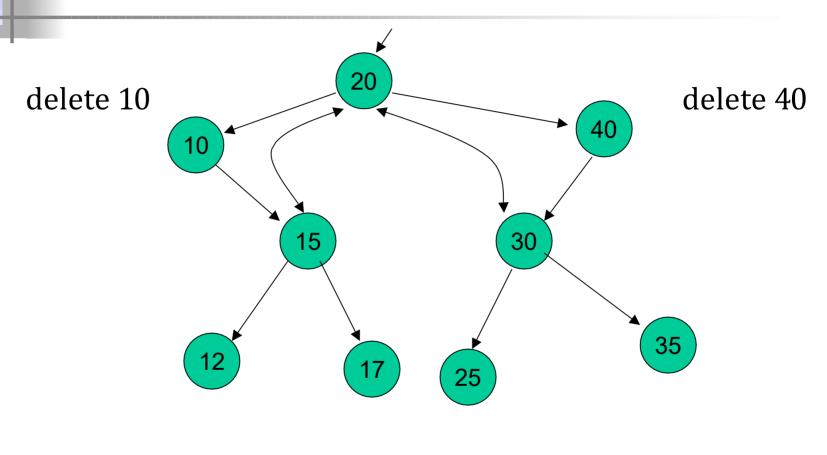


• Delete 5



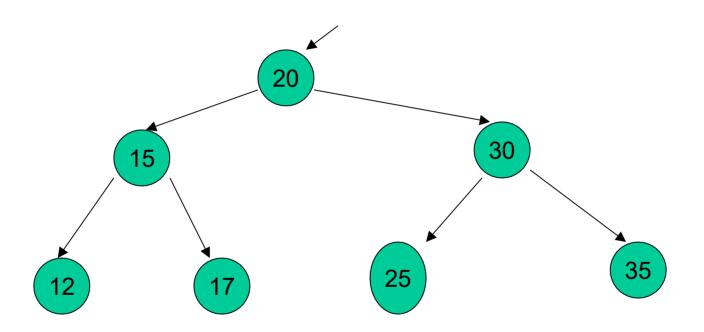


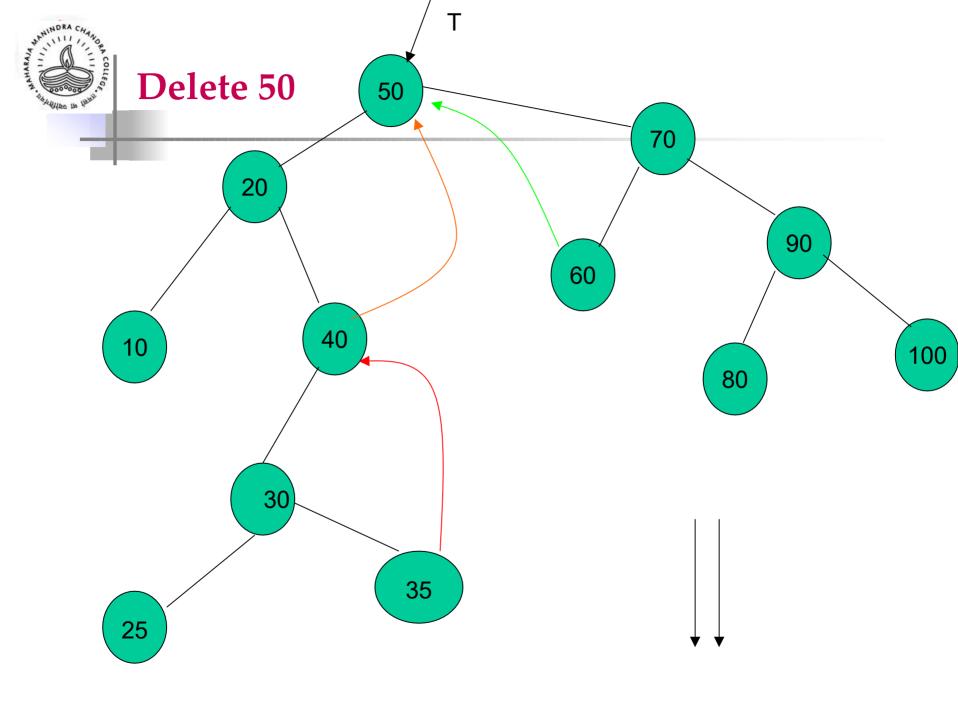






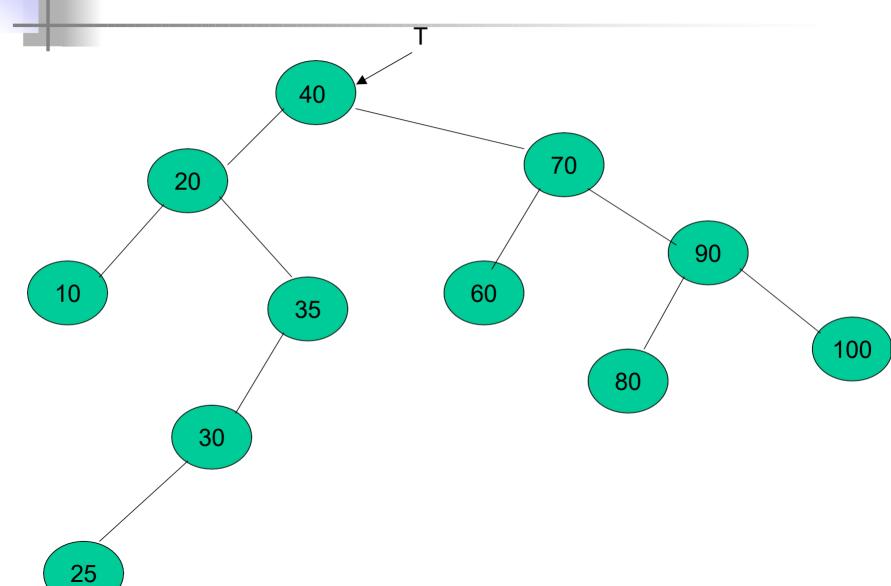






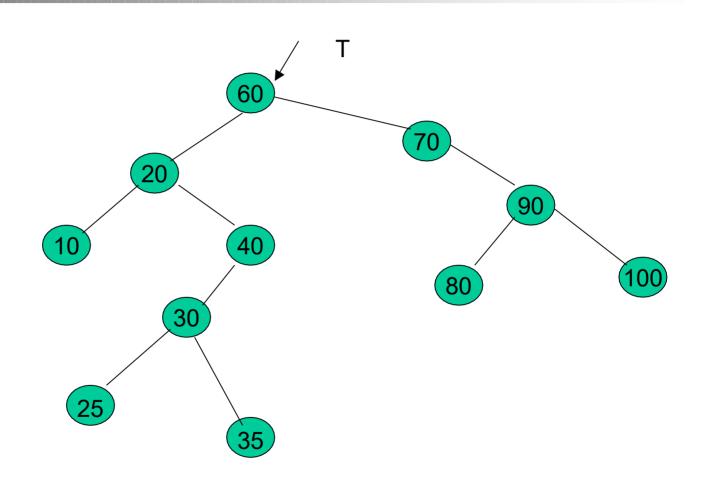


Result 1





Result 2





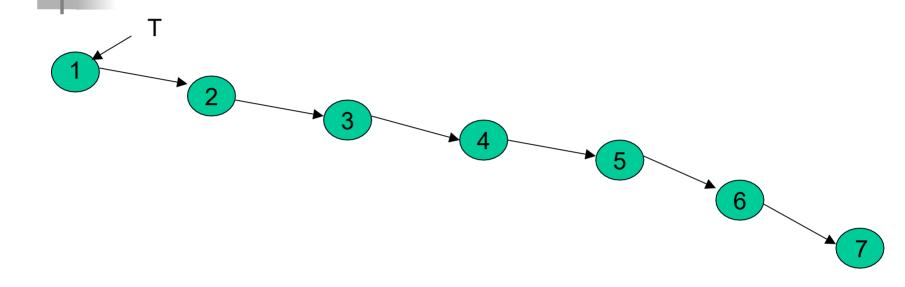
Problem of BST

- Average case complexity of search, insertion and deletion operations is O(log₂ n), where n is the no of nodes in the tree.
- The height of a BST depends on the sequence of insertion and deletion of keys.
- An extreme case:
 Draw a BST for the following sequence of insertions:

1, 2, 3, 4, 5, 6, 7



Problems of BST ...



The tree degenerates into a linked list.

The worst case complexity of search, insertion and deletion are O(n).

Remedy: Balanced tree.



Height Balanced Tree (AVL Tree)

- Invented by Adelson-Velskii, Landis
- AVL tree is a BST where at each node (including the root node) the left sub-tree and the right sub-tree do not differ in height by more than one.

$$|h_L - h_R| <= 1$$



Balance Factor

 Balance Factor (BF) of a node is the difference between the heights of its left and right sub-trees.

$$BF = h_L - h_R$$

$$BF = -1$$
 right high



AVL Tree Operations

- 1. Search a key
- 2. Find max & Find min

Same as BST

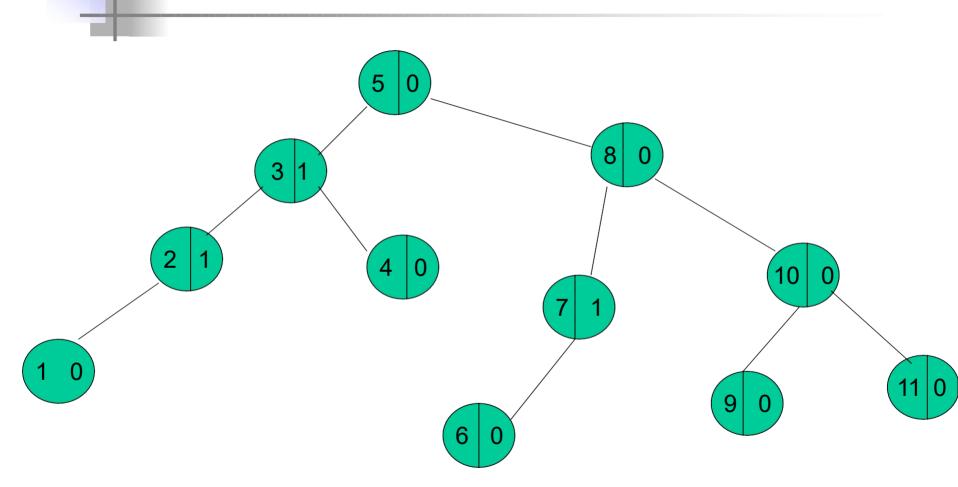
3. Find Kth max & k th min

- 4. Insert a Key
- 5. Delete a Key

Insert / Delete as in BST; then rebalance the resultant tree if necessary

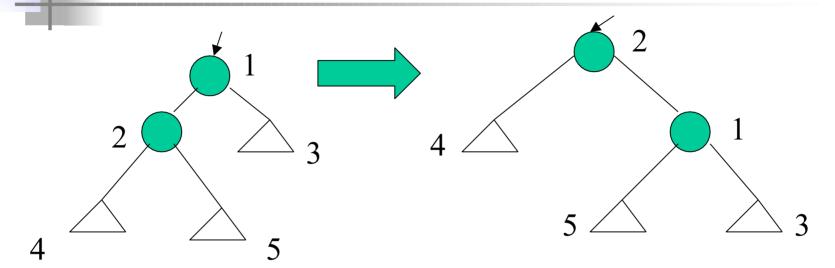


AVL Tree Example





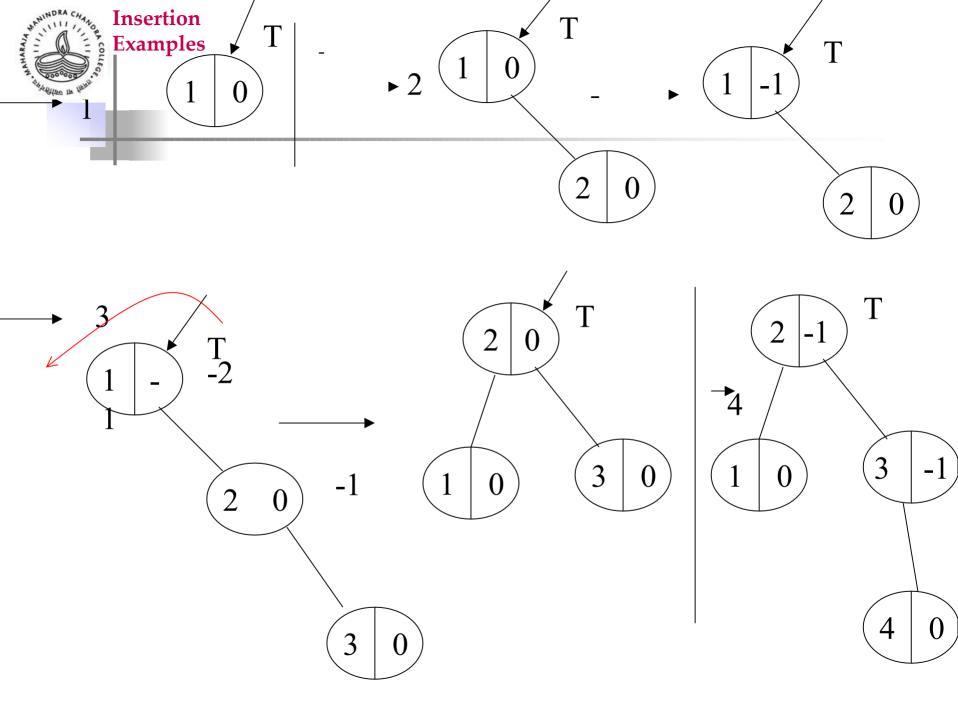
Rebalancing needs Rotation



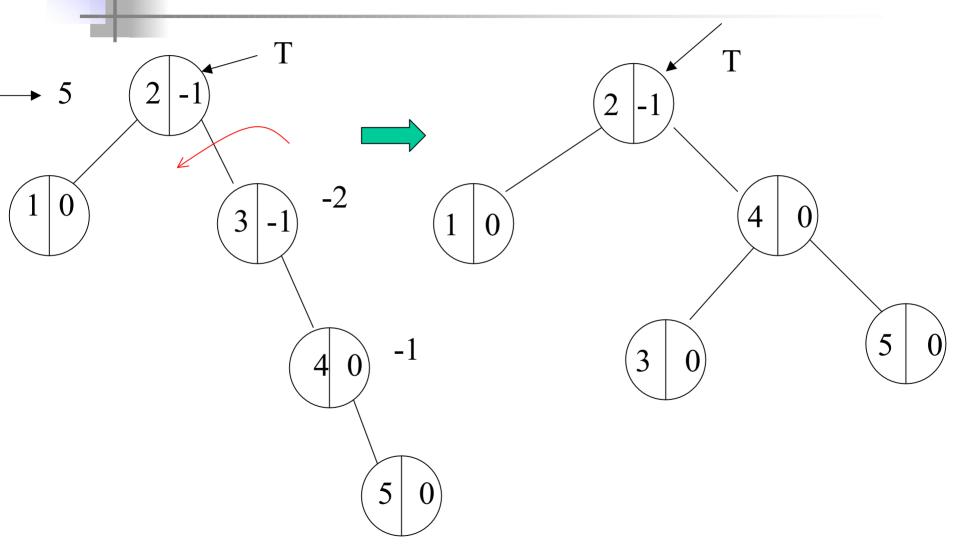


Right Rotation

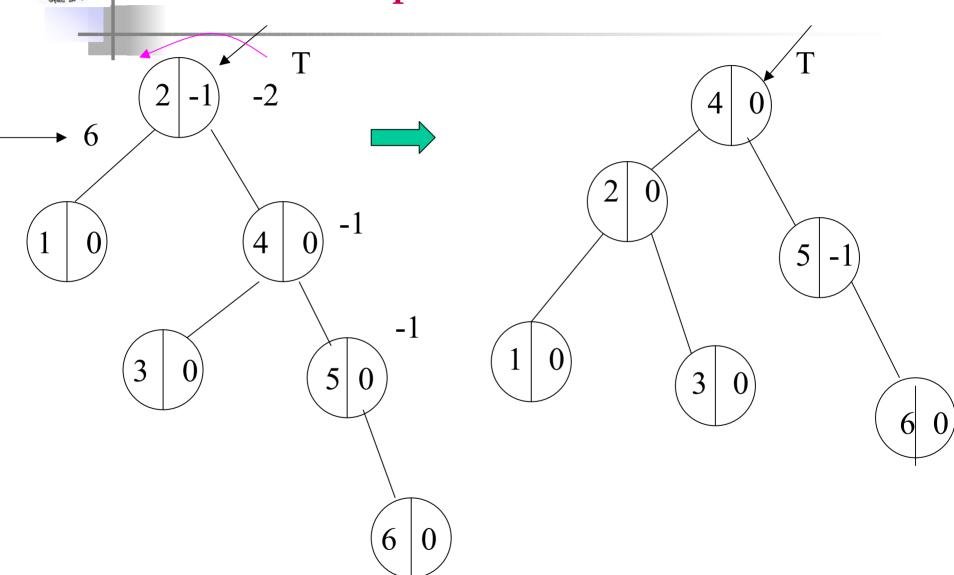
```
avltree * rotate-right (avltree * t) {
    avltree * temp;
temp = t → left;
t → left = temp → right; temp →
    right = t; return temp;
}
```



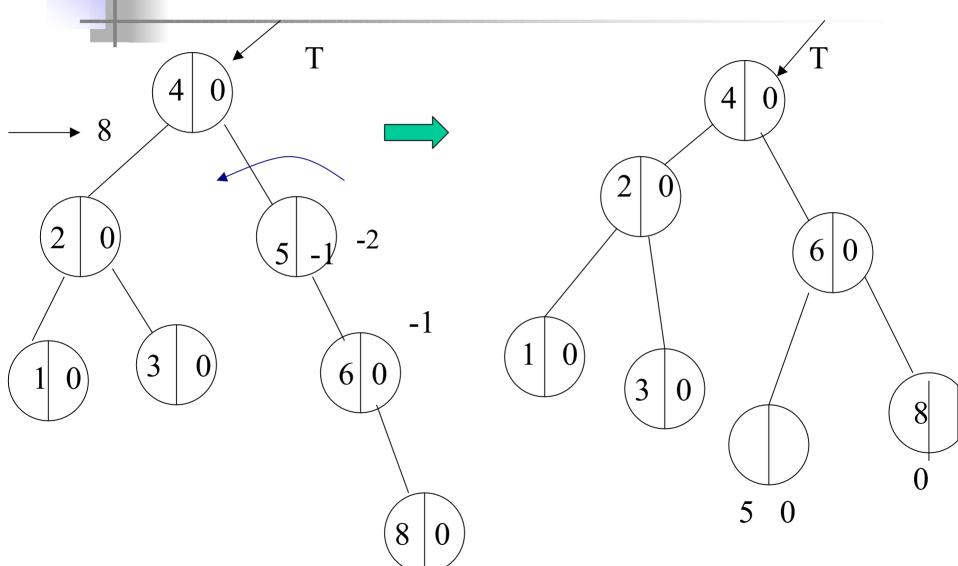


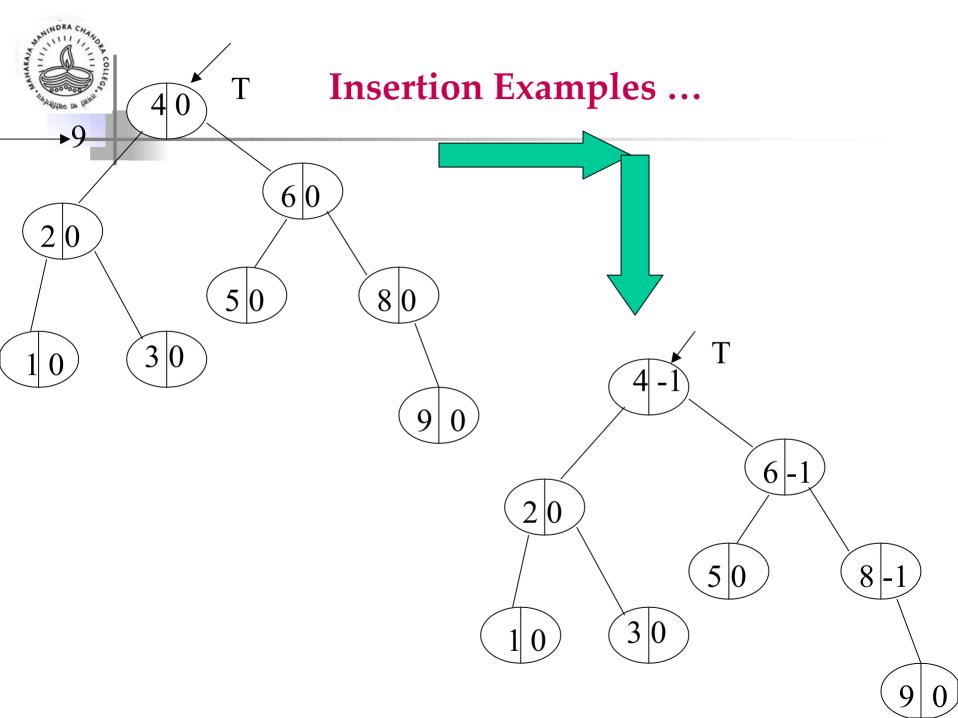




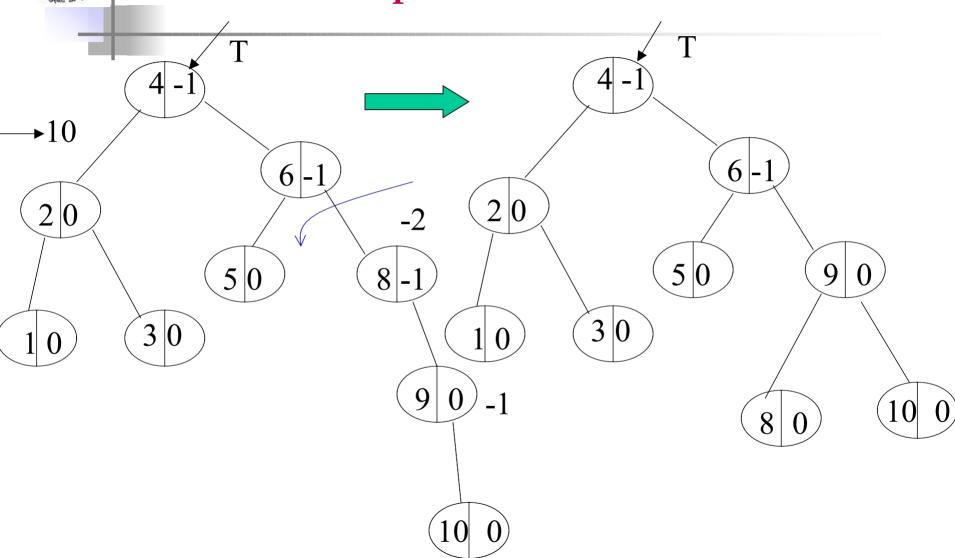






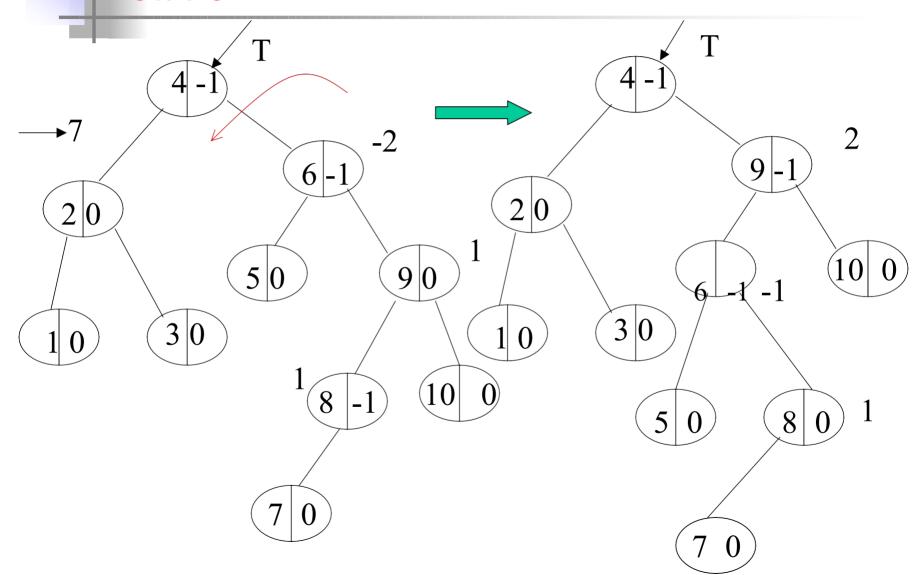






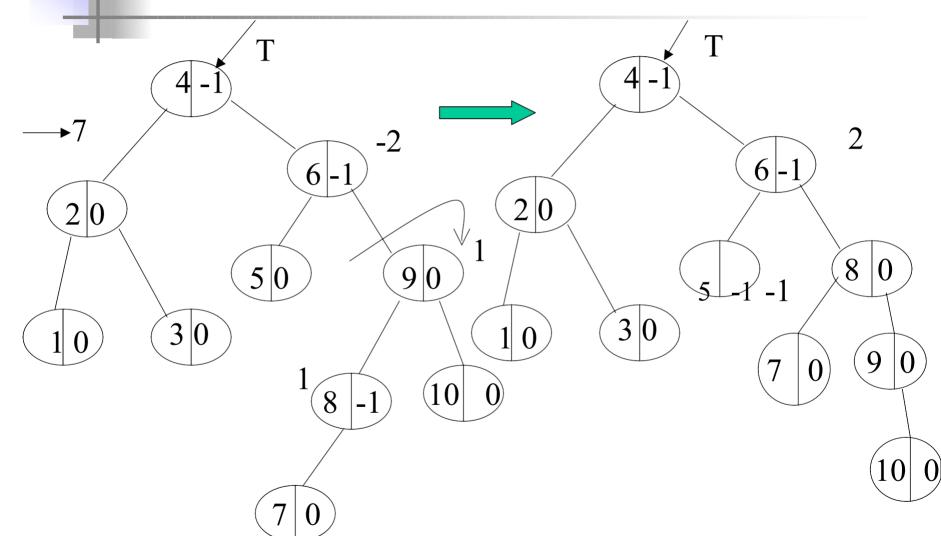


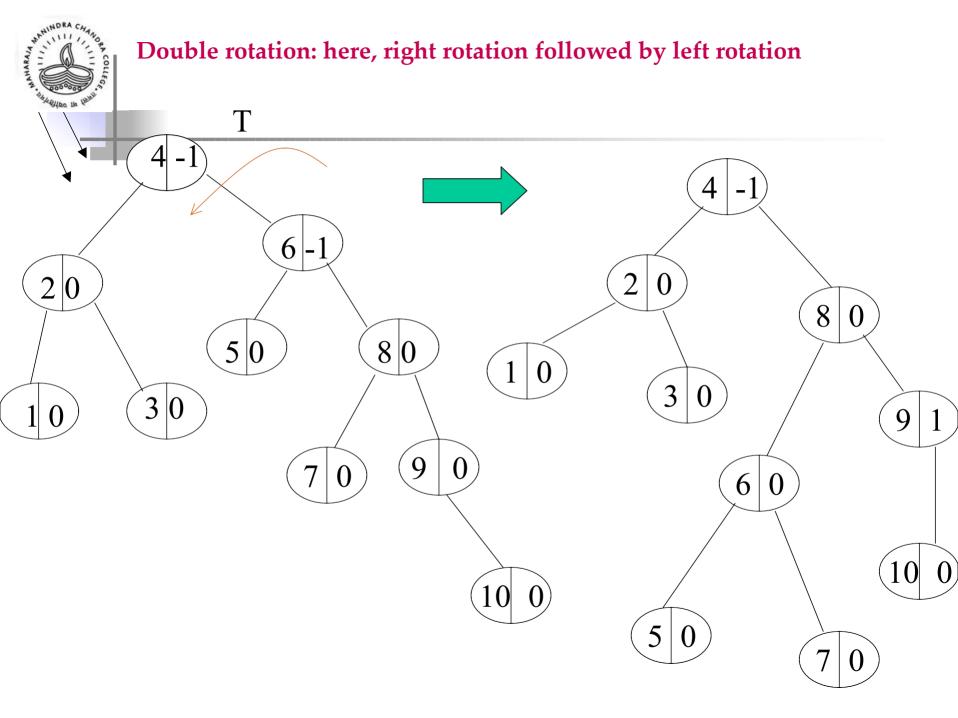
Tree remains unbalanced even after rotation





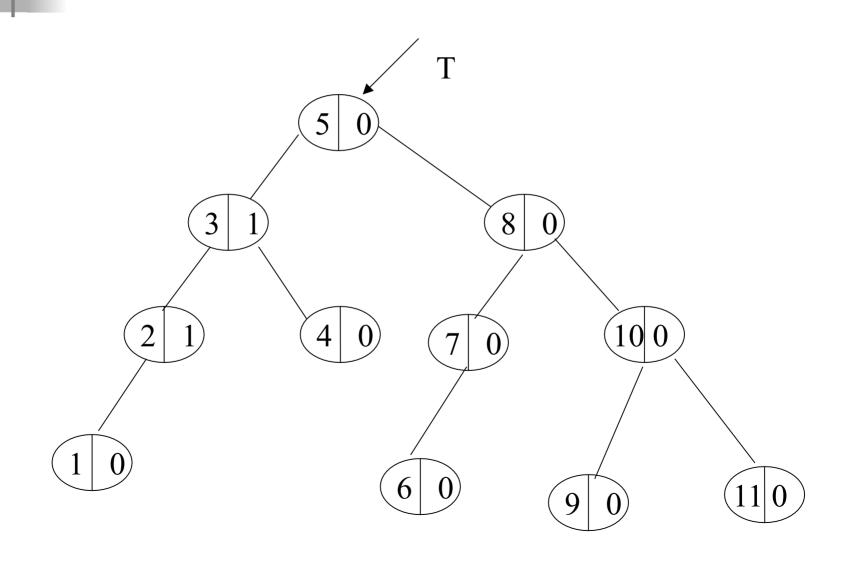
Right rotate the right child

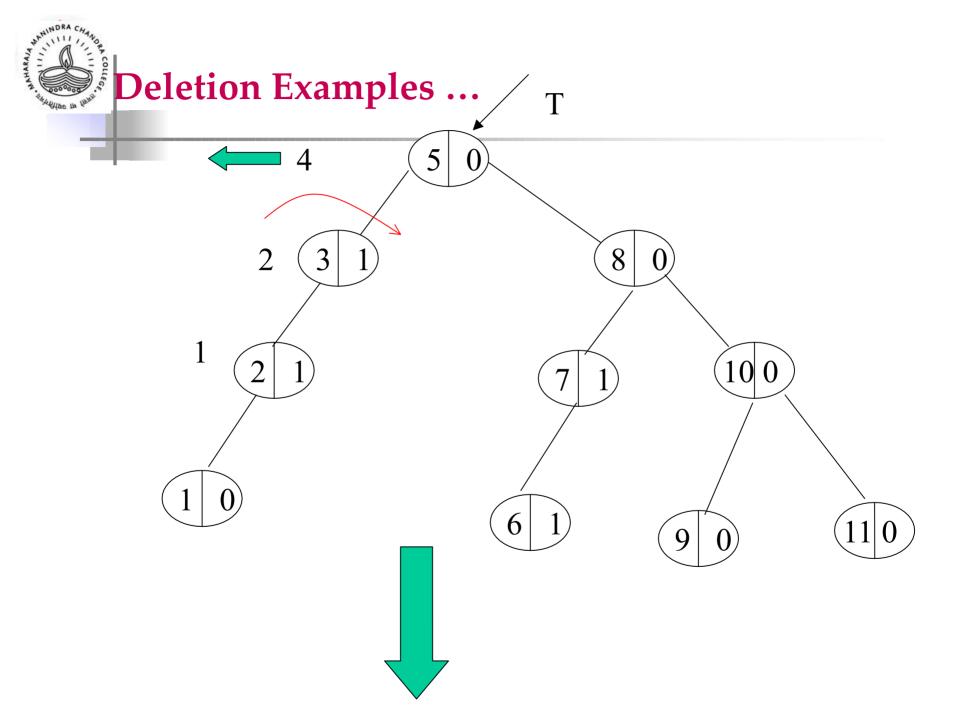




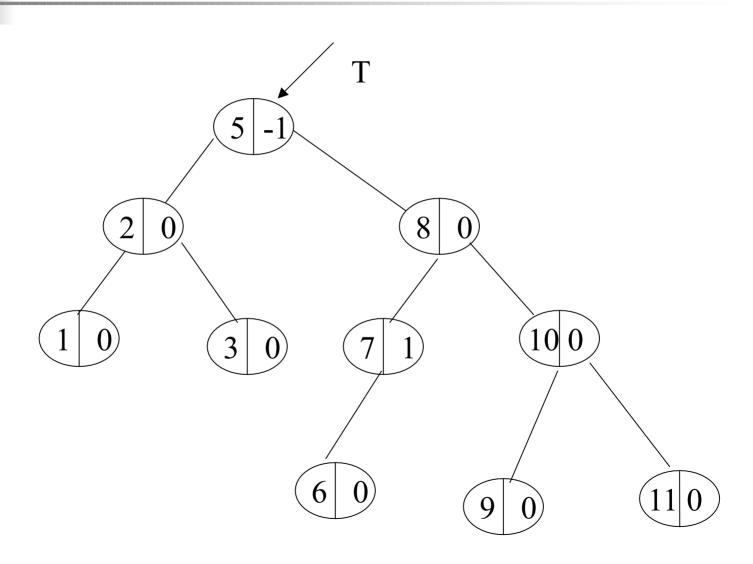


Deletion Examples

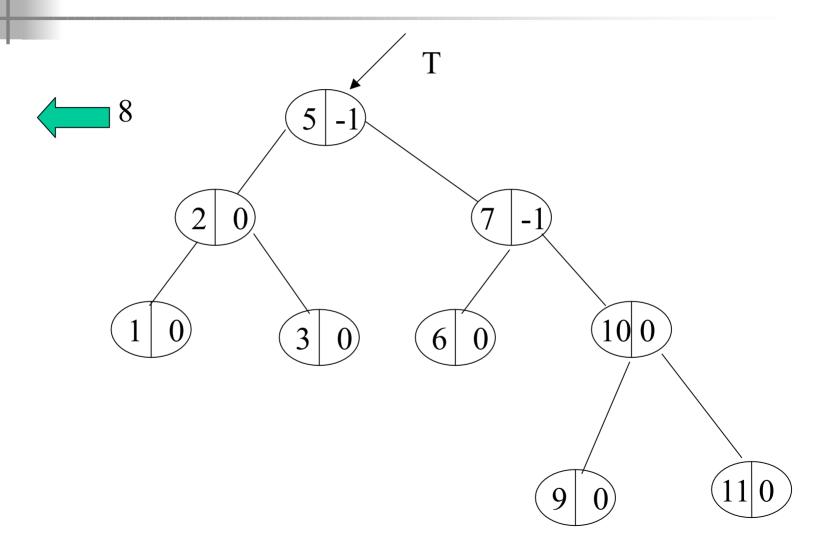




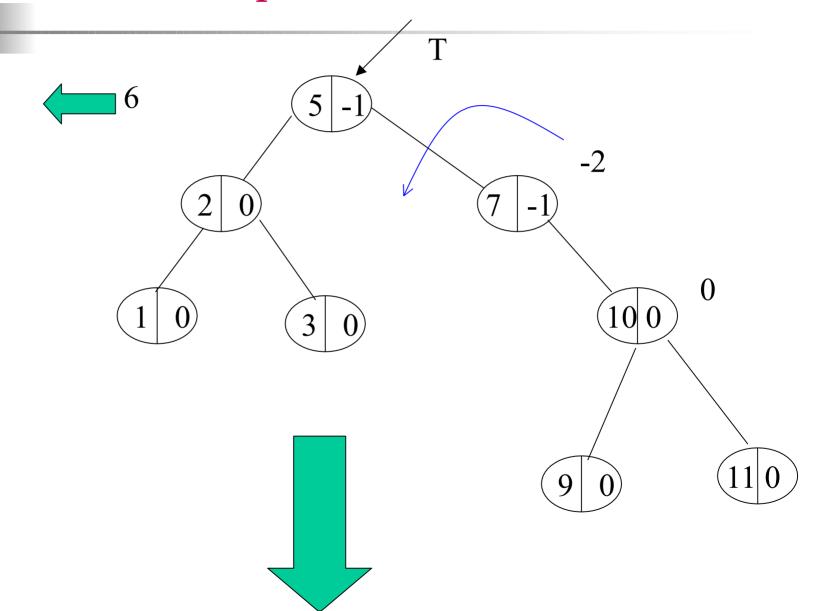




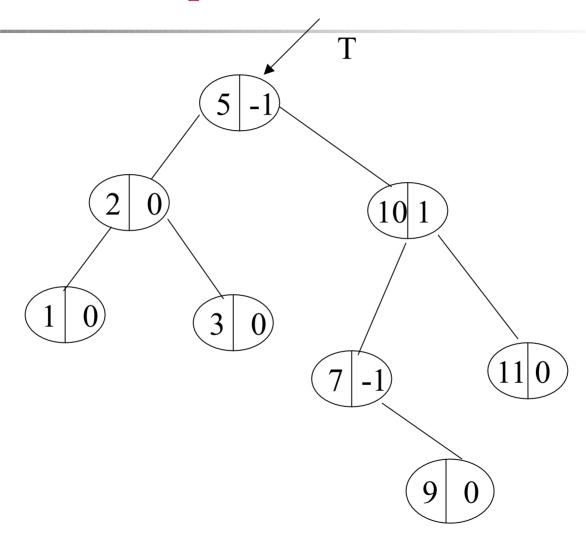














Conclusion

- Height of a height-balanced (AVL) Tree is guaranteed to be O(log n), n being the no. of nodes.
- The insertion/deletion step takes at most O(log n) time.
- Each rebalancing step, i.e., rotation (possibly double rotation) and updation of BF takes a constant amount of time.
- The rebalancing may go up to the root. Thus, there can be at most O(log n) rebalancing steps.
- Thus the overall complexity of insertion/deletion is O(log n).